

Math 132: Differential Topology

§ Orientation

Def

Suppose V is a finite diml real vector space,

and $\beta = \{v_1, \dots, v_k\}$ and $\beta' = \{v'_1, \dots, v'_k\}$ are two ordered basis.

Then there is a unique linear isomorphism $A: V \rightarrow V$ such that $\beta' = A\beta$.

We say β and β' are equivalently oriented if $\det A > 0$.

This gives an equivalence relation on the set of all ordered basis of V ,
and there are exactly two equivalence classes ($GL(V)$ has 2 components).

Def An orientation of V is a choice of one of those two equivalence classes.

An orientation induces a sign (+ or -) on any ordered basis of V .

* When $V=0$, we separately define its orientation to be a choice of a sign $\in \{\pm\}$.

Ex Say, $V = \mathbb{R}^2$ and choose $[(e_1, e_2)]$ for the orientation.

Then

$\begin{matrix} 2 \\ \uparrow \\ \downarrow \\ \rightarrow \\ \leftarrow \end{matrix}_1, \begin{matrix} 2 \\ \swarrow \\ \searrow \\ \rightarrow \\ \leftarrow \end{matrix}_1, \begin{matrix} 2 \\ \leftarrow \\ \rightarrow \\ \uparrow \\ \downarrow \end{matrix}_1, \begin{matrix} 2 \\ \rightarrow \\ \leftarrow \\ \uparrow \\ \downarrow \end{matrix}_1, \begin{matrix} 2 \\ \nearrow \\ \searrow \\ \rightarrow \\ \leftarrow \end{matrix}_1, \dots$ are positively oriented,

while $\begin{matrix} 1 \\ \uparrow \\ \downarrow \\ \rightarrow \\ \leftarrow \end{matrix}_2, \begin{matrix} 1 \\ \swarrow \\ \searrow \\ \rightarrow \\ \leftarrow \end{matrix}_2, \begin{matrix} 1 \\ \leftarrow \\ \rightarrow \\ \uparrow \\ \downarrow \end{matrix}_2, \begin{matrix} 1 \\ \rightarrow \\ \leftarrow \\ \uparrow \\ \downarrow \end{matrix}_2, \dots$ are negatively oriented

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Note, if V and W are oriented real vector spaces of the same dimension, then any isomorphism $A: V \rightarrow W$ either preserves or reverses orientation.

Def An orientation of M , a manifold with boundary,

is a smooth choice of orientations for all tangent spaces $T_p M$.

↑
i.e. around each $p \in M$, there is a local parametrization $h: U \rightarrow M$, $U \subset \mathbb{H}^m \subset \mathbb{R}^m$, such that $dh_u: T_u U \cong \mathbb{R}^m \rightarrow T_{h(u)} M$ preserves orientation for all $u \in U$, where \mathbb{R}^m is given the standard orientation $[(e_1, \dots, e_m)]$.

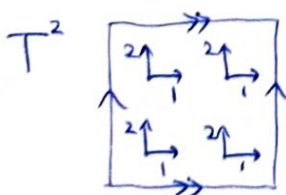
A smooth map ^{between oriented manifolds of same dim.} whose derivative preserves orientations at every point is called an orientation-preserving map.

Ex Not all manifolds can be oriented!

Möbius band



Ex



\rightsquigarrow orientable

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Prop A connected, orientable manifold with boundary admits exactly two orientations.

proof) The set of points at which two orientations agree and the set where they disagree are both open.

Consequently, two orientations of a connected manifold are either identical or opposite. ■

Rmks:

• The product $M \times N$ of two oriented manifolds (where one of them is boundaryless) acquires a product orientation, for if α and β are ordered basis for $T_p M$ and $T_q N$, then $(\alpha \times 0, 0 \times \beta)$ is an ordered basis for $T_{(p,q)}(M \times N) \cong T_p M \times T_q N$.

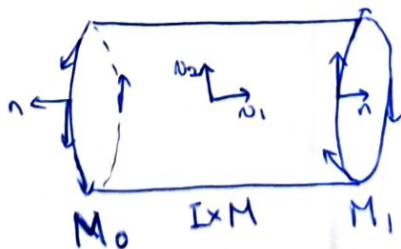
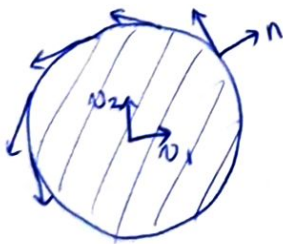
• An orientation of M induces a boundary orientation on ∂M ;

this can be done by declaring the sign of any ordered basis

$\beta = \{v_1, \dots, v_{m-1}\}$ of $T_p(\partial M)$ to be the sign of the ordered basis

$\{n_p, \beta\} = \{n_p, v_1, \dots, v_{m-1}\}$, where n_p is the outward unit normal at p .

Ex



↑ note, opposite orientation!

$\Rightarrow \partial(I \times M) = M_1 - M_0$

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If $V = V_1 \oplus V_2$, the orientations on any two of V, V_1, V_2 induces a direct sum orientation on the third. (The ordering of summands is important!)

We can use this to orient $f^{-1}(P)$ if $f: M \rightarrow N \underset{P}{\cup} P$, $f \uparrow P, f|_M \uparrow P$ and M, N, P are all oriented.

Let $N_x(Q; M)$ be the orthogonal complement of $T_x Q$ in $T_x M$

so that $T_x M = N_x(Q; M) \oplus T_x Q$.

By transversality, $T_y N = df_x(N_x(Q; M)) \oplus T_y P$.

orientation on $T_x Q$!

Prop $\partial f^{-1}(P) = (-1)^{\text{codim } P} (f|_M)^{-1}(P)$.

proof sketch

$T_x M = N_x(Q; M) \oplus \mathbb{R} \cdot \underbrace{n_x}_{\text{outward normal to } \partial Q} \oplus T_x(\partial Q)$
 $= \mathbb{R} \cdot n_x \oplus N_x(Q; M) \oplus T_x((f|_M)^{-1}(P))$

\Rightarrow the orientations differ by $(-1)^{\text{codim } Q} = (-1)^{\text{codim } P}$ ■